

Coherent Scatterers (CSs) Detection for Glacier Monitoring by means of TerraSAR-X Data

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Introduction

- ❑ **Coherent Scatterers (CSs)**: relevant class of point (-like) scatterers.
 - Important characteristic of CSs: stable spectral correlation.
 - Spectral correlation techniques have been proposed for their detection.
 - Advantage compared with other point scatterers: the estimation of CSs is possible with a single image basis.

- ❑ **Why CSs?**
 - Point scatterers are the only kind of scatterers that can give us information about the phase (not affected by the speckle).

- ❑ CSs detection investigated primarily in urban environments and on the basis of airborne data.

- ❑ Analysis of the potential of CSs detection for natural scenarios (like ice and glacier terrain) in terms of wide-band spaceborne SAR systems (TerraSAR-X) and possible applications with time series data.



CSs Detection

□ Different approaches for the detection of CSs:

☛ **Sublook Coherence Approach**: based on the cross-correlation of two spectral sub-bands. Scatterers with high sublook correlation values are considered as detected CSs.

☛ **Sublook Entropy Approach**: based on the cross-correlation of multiple spectral sub-bands. In this case, the measure to use is the entropy among the sublook images.

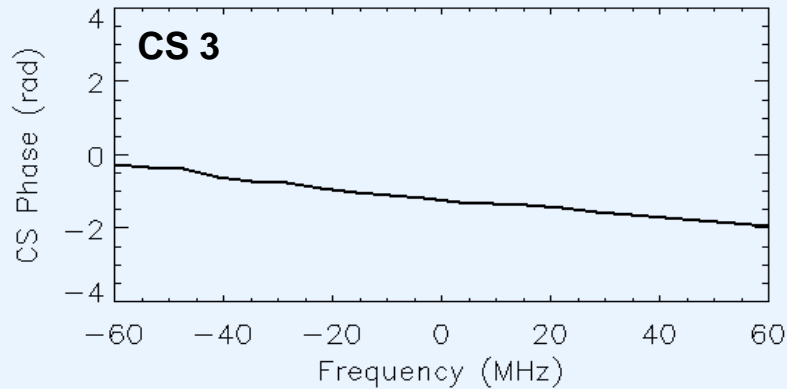
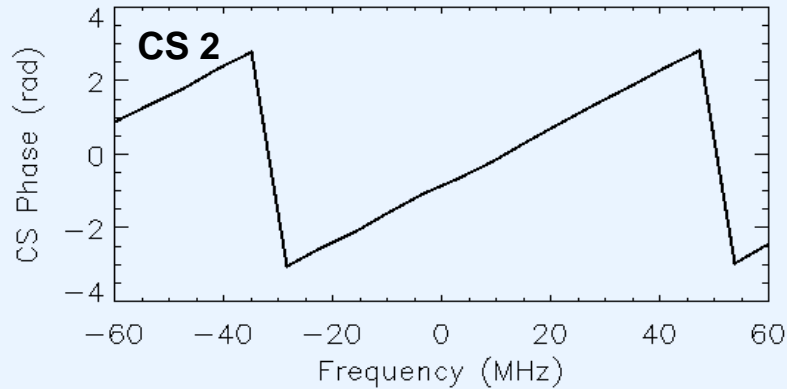
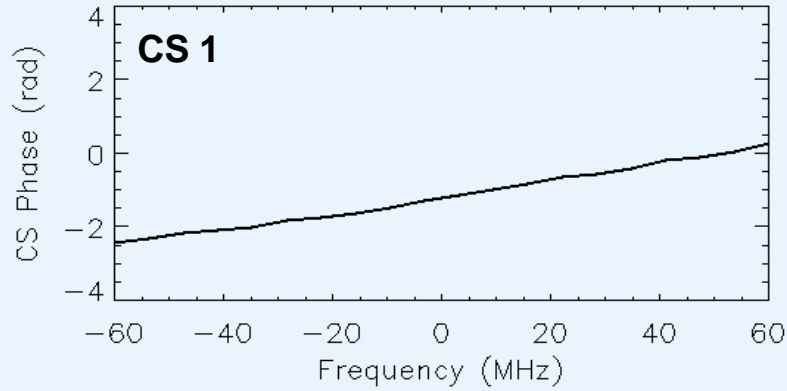
- It allows a more flexible detection with respect to the spectral characteristics of the individual CSs.

☛ **Phase Variance Approach**: based on the deterministic phase pattern across the spectrum characteristic of the CSs.

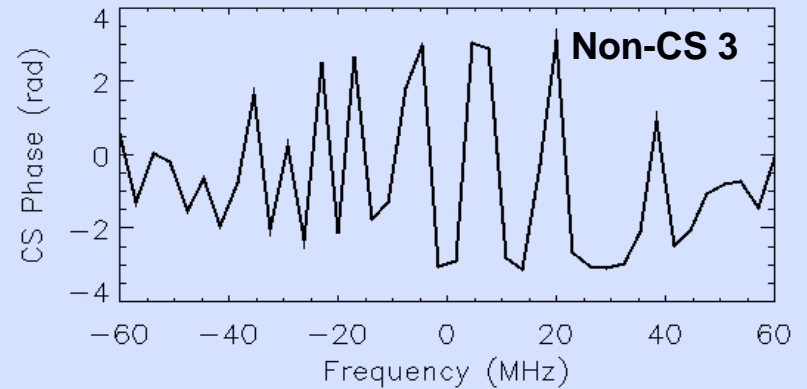
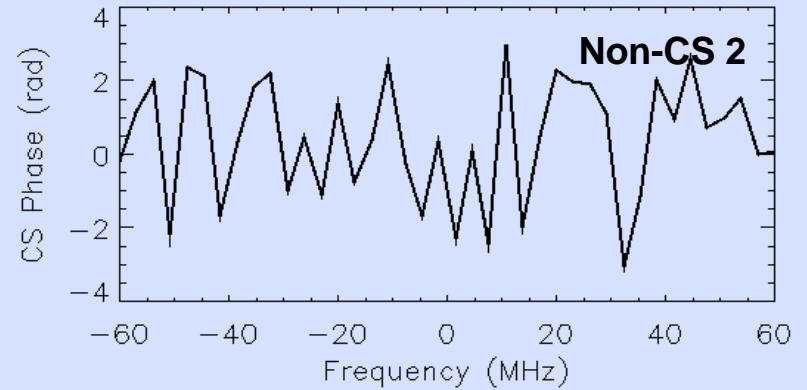
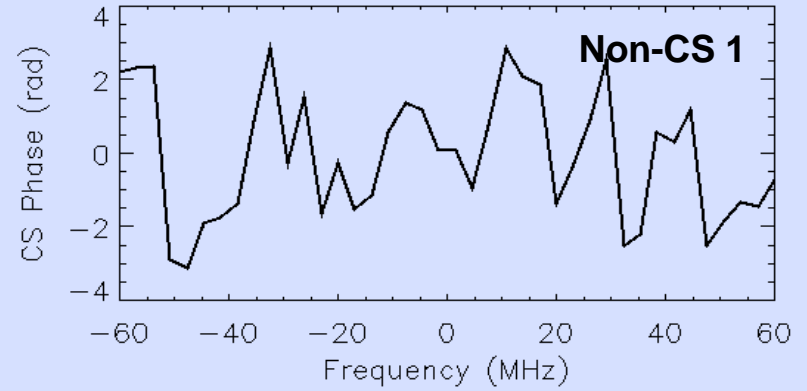
- It allows a widely preservation of the spatial resolution in the CSs detection.

Phase of CSs and Non-CSs as a Function of Frequency

Coherent Scatterers

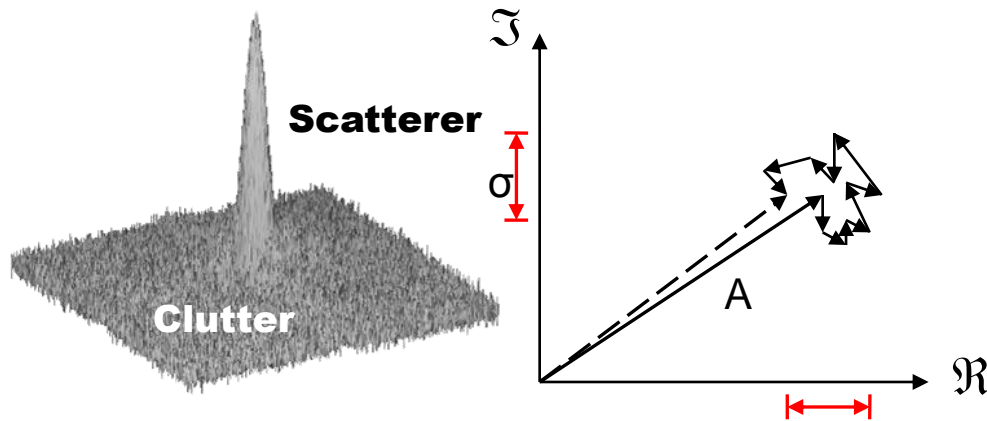


Distributed Scatterers



CSs Statistical Model

Assumption: One dominant (point-like) scatterer + Clutter

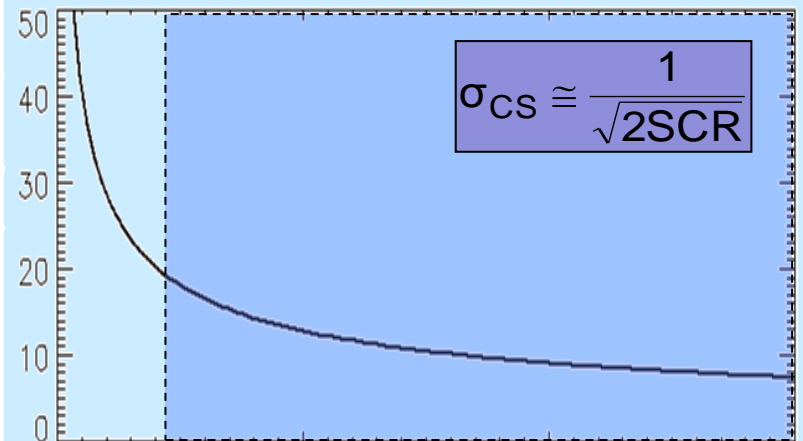
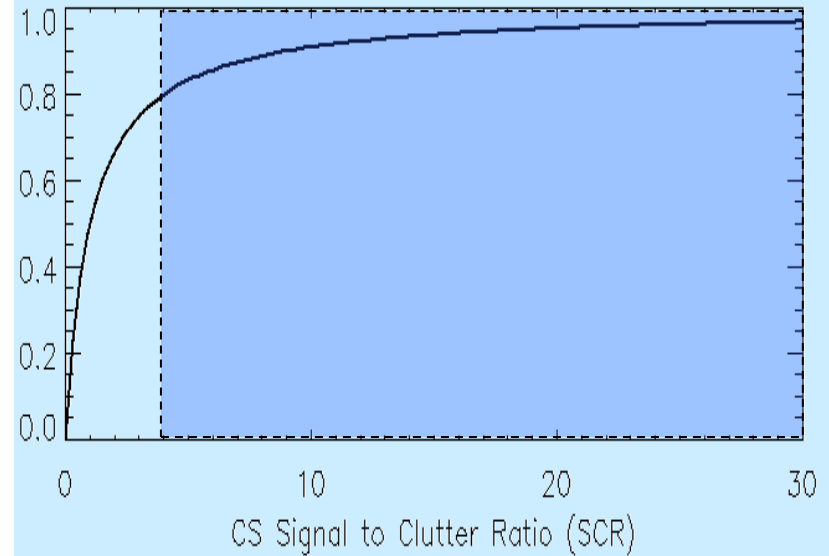


Signal to Clutter Ratio:
$$SCR = \frac{A^2}{2\sigma^2} = \frac{Y_{sub}}{1 - Y_{sub}} = R$$

Sublook Coherence:
$$Y_{sub} = \frac{A^2}{A^2 + 2\sigma^2} = \frac{1}{1 + SCR^{-1}}$$

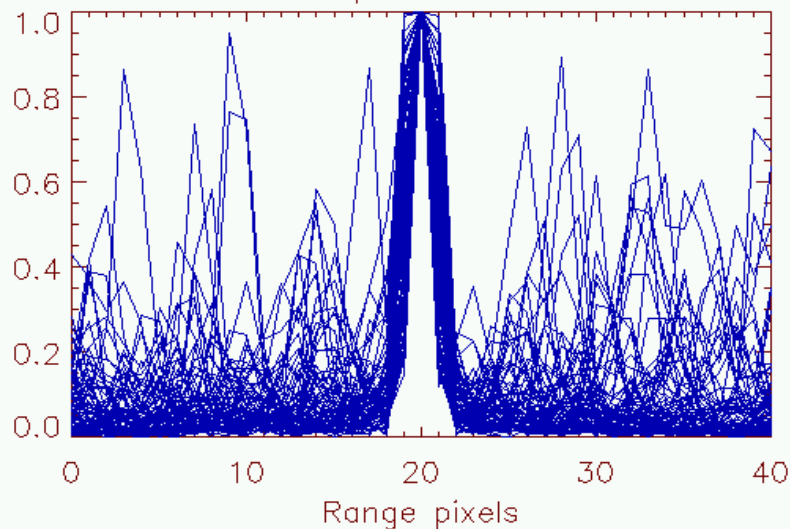
CSs Phase Variance:
$$\sigma_{CS}^2 \cong \frac{1}{2 SCR} \quad \text{for large SCR}$$

Sublook coherence x CS SCR

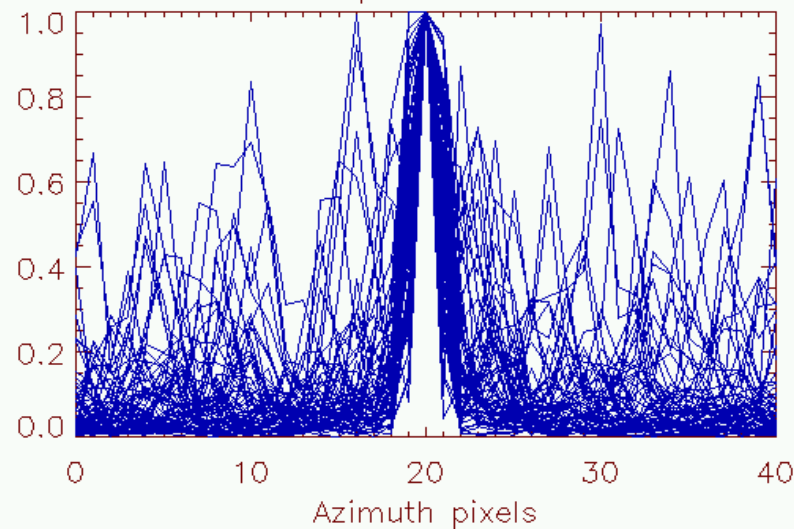




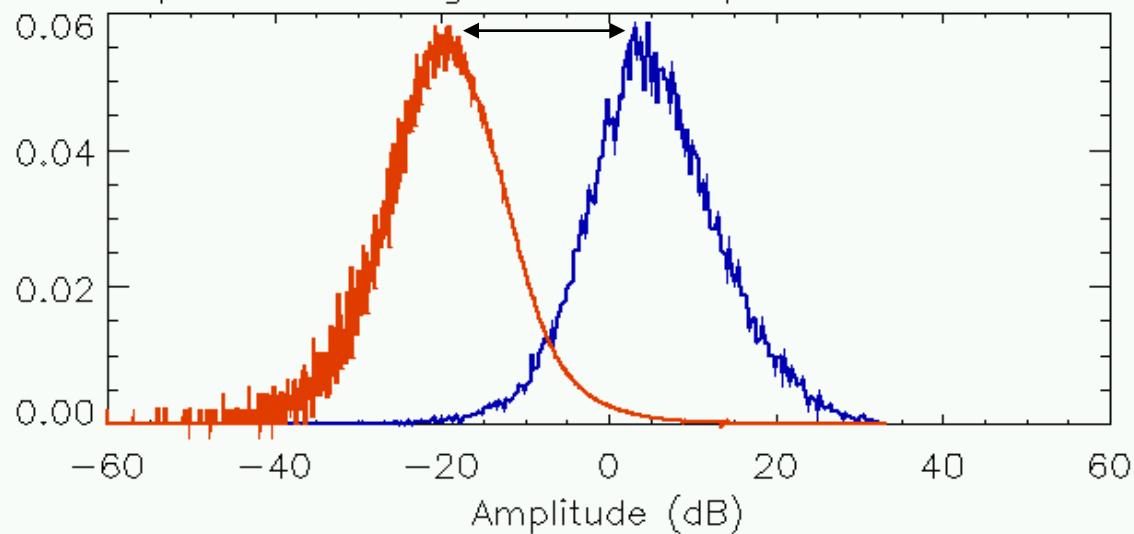
Normalized amplitude of several CSs



Normalized amplitude of several CSs



Amplitude histogram of all pixels and of CSs



Test site: Paris, France

Sensor: TerraSAR-X

Bandwidth: 300 MHz

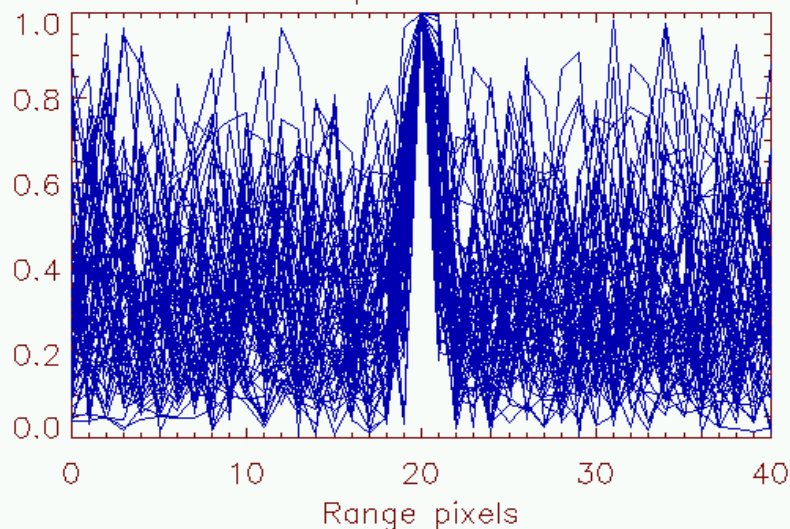
Mode: Spotlight



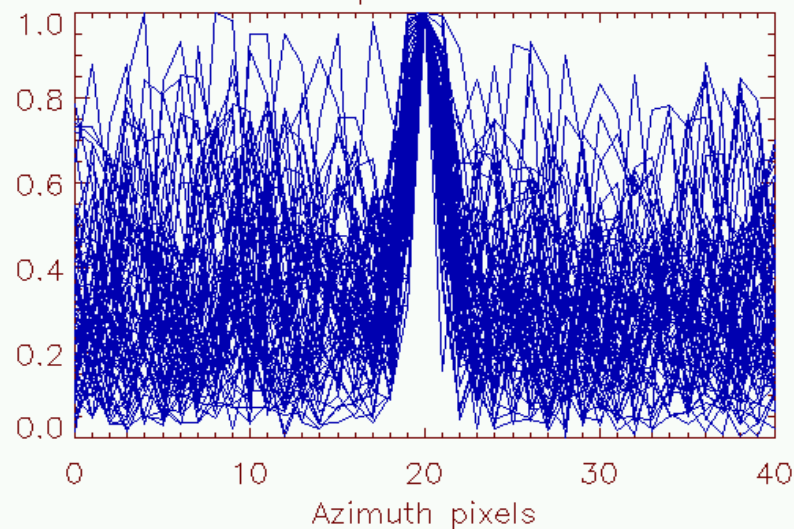
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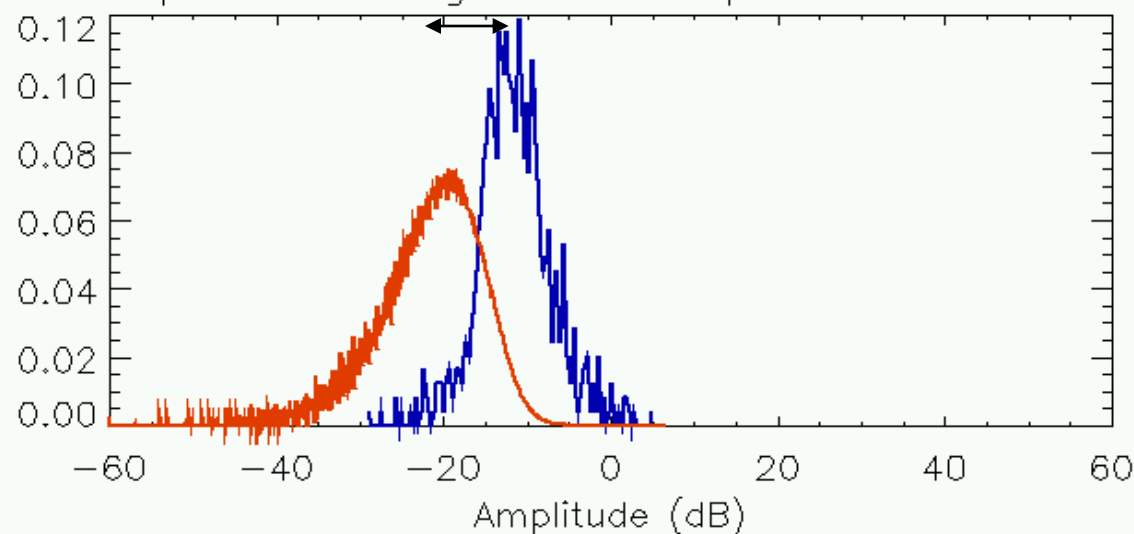
Normalized amplitude of several CSs



Normalized amplitude of several CSs



Amplitude histogram of all pixels and of CSs



Test site: Salar de Uyuni, Bolivia

Sensor: TerraSAR-X

Bandwidth: 300 MHz

Mode: Strip-map




IMAGE1: 19-06-09

IMAGE2: 30-06-09
Test site:

IMAGE3: 11-07-09

➤ Helheim Glacier

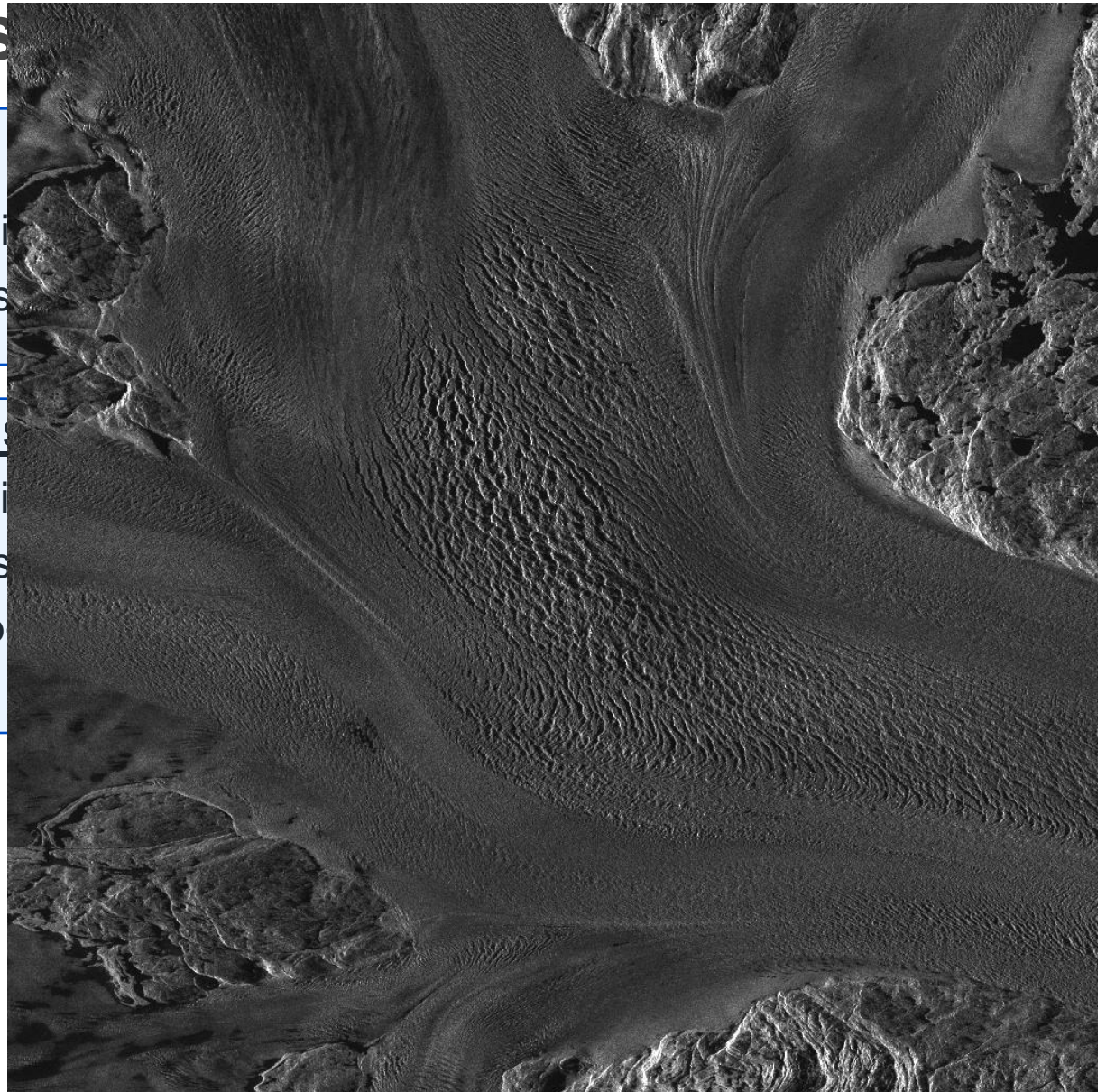
➤ One of the fastest

SAR acquisitions

➤ TerraSAR-X time

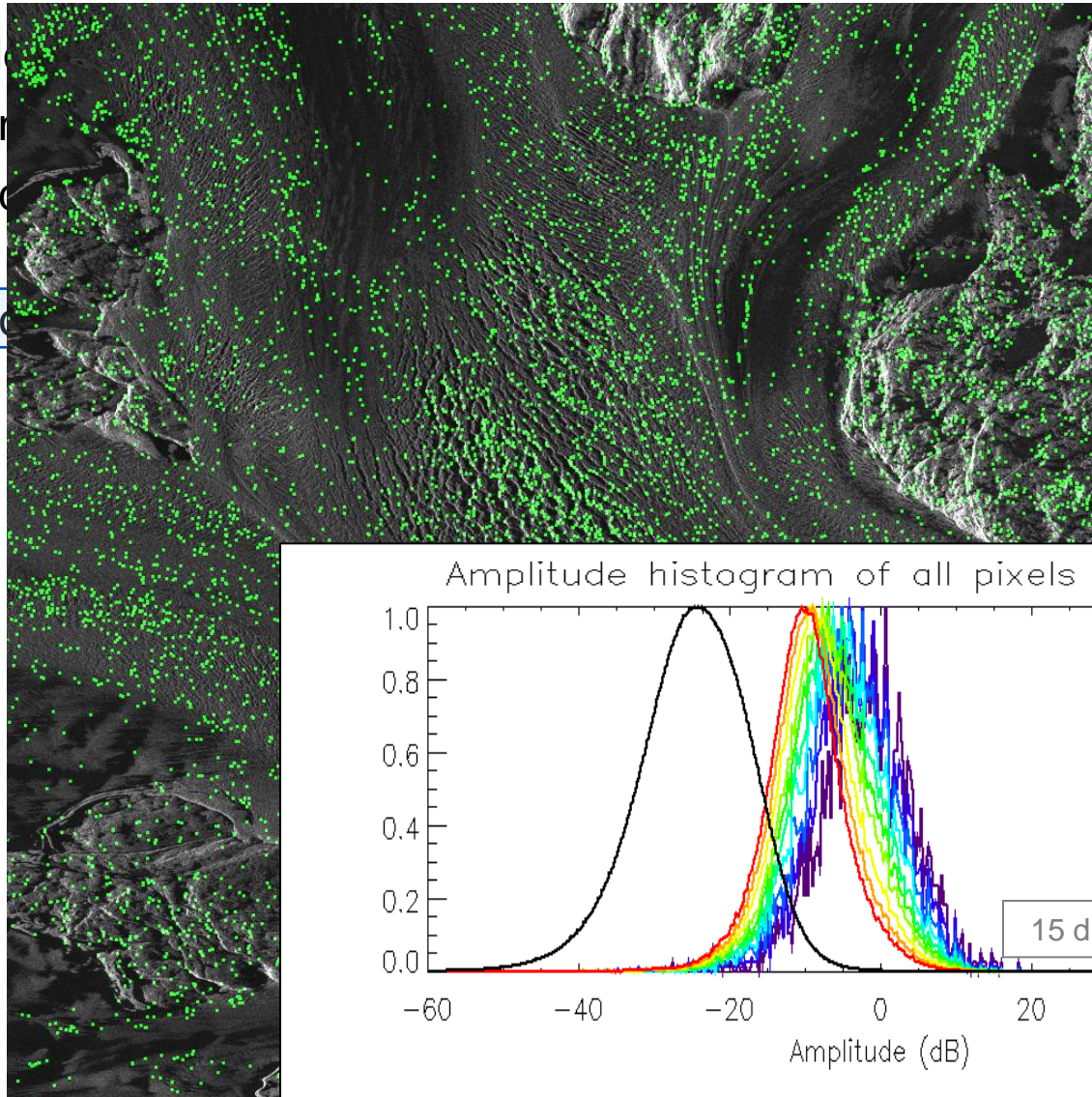
➤ Period: August

➤ 11 days, Strip
angle.



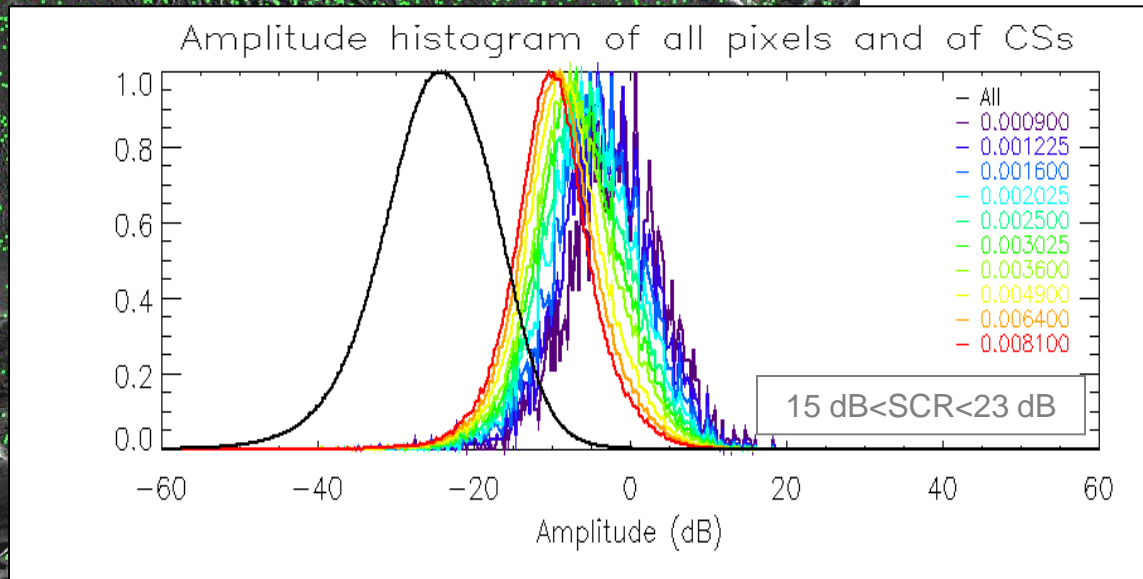
Results: Range CSs Detection

- 10 sub
- Spanning
- Phase of
- these 1
- Threshold



bandwidth.

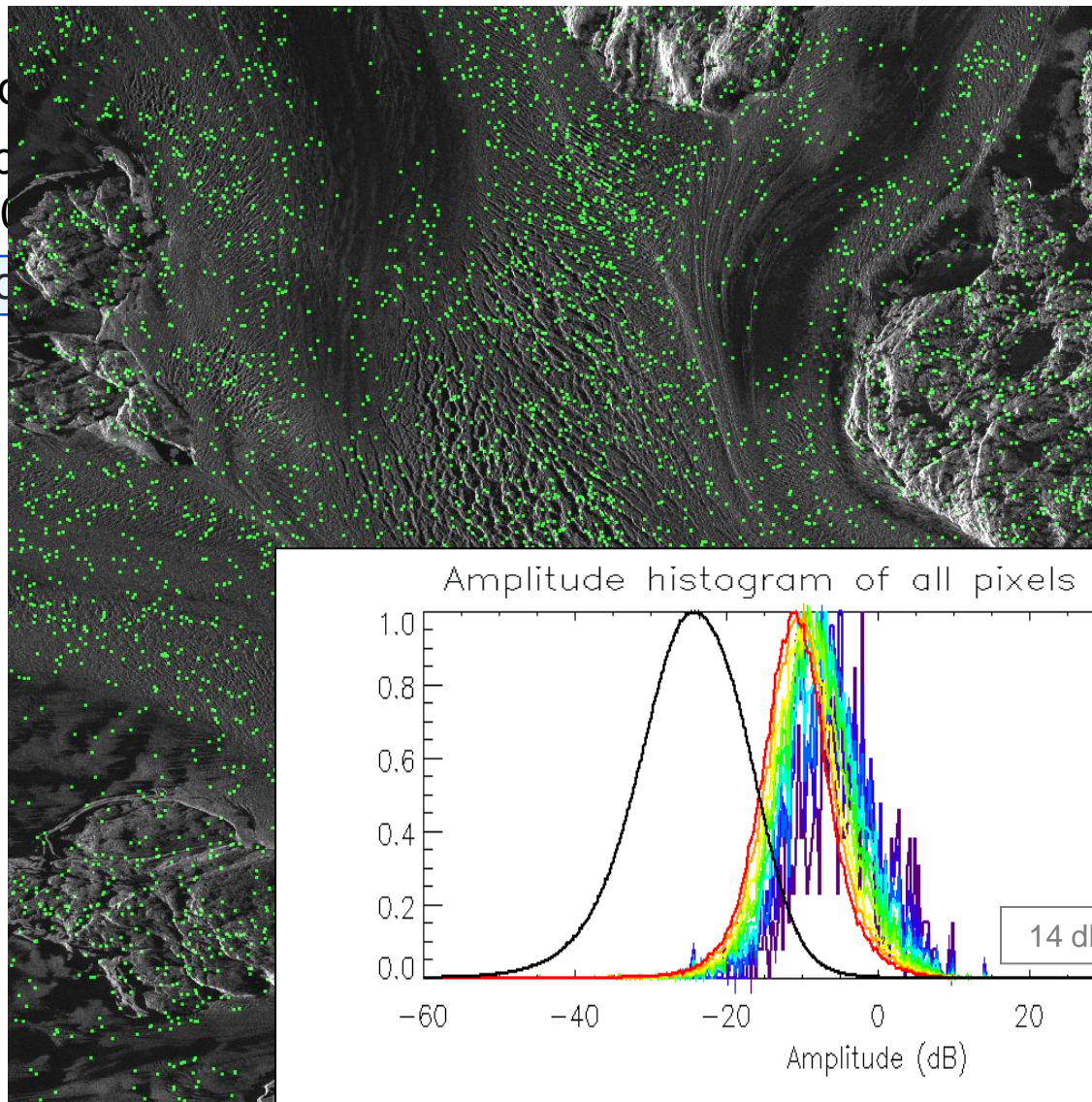
pixel across



Results: Azimuth CSs Detection

- 10 sublo
- Phase of these 10
- Threshold

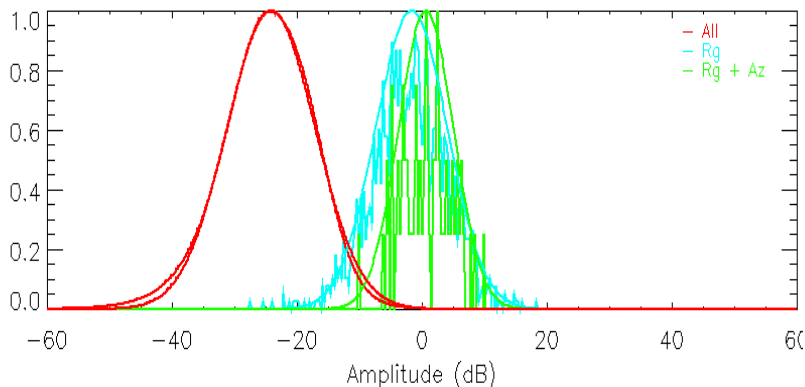
Pixel across



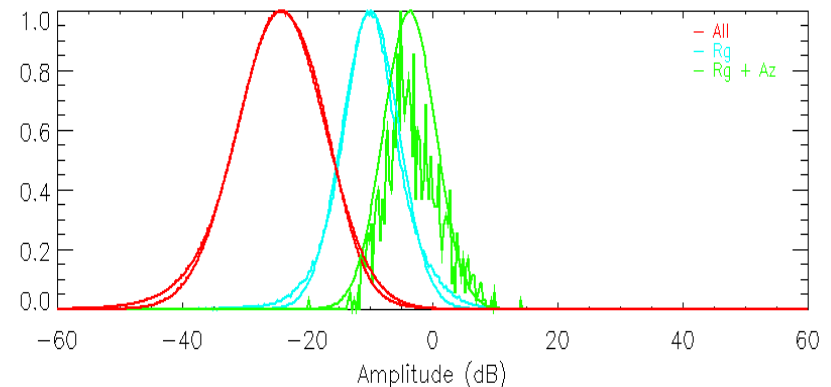
Detection Analysis: Common detection

Improvement of Range Detection using Azimuth Information

- 10 sublooks of 60 MHz each out of the 150 MHz range bandwidth are formed and the variance σ^2 of the phase derivative for every pixel is estimated.
- CSs are detected for a given range threshold ($\sigma^2 = 0.0009$ and 0.0081 rad^2).
- 10 sublooks of 1106 Hz each out of the 2765 Hz azimuth bandwidth and the variance of the phase derivative for every pixel is estimated.
- From the CSs detected in range, the ones that have an azimuthal variance $\sigma^2 < 0.0016 \text{ rad}^2$ are selected.



$$\text{SCR}_{\text{improv}} = 2 \text{ dB}$$

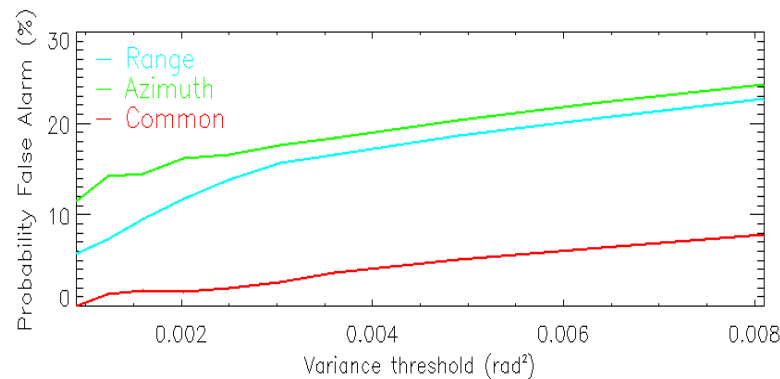
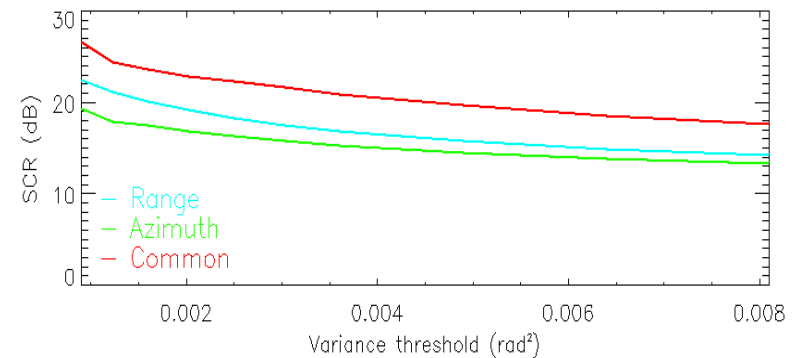
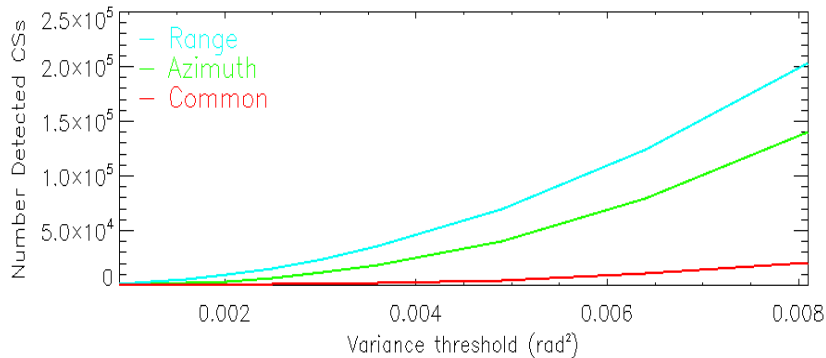


$$\text{SCR}_{\text{improv}} = 6 \text{ dB}$$

Detection Analysis: Common detection (II)

□ Detection in common

- Comparison between range only, azimuth only and common range-azimuth detection.
- Common detection: only the CSs that have a phase derivative variance σ^2 lower than a given threshold in both direction are considered as CSs.

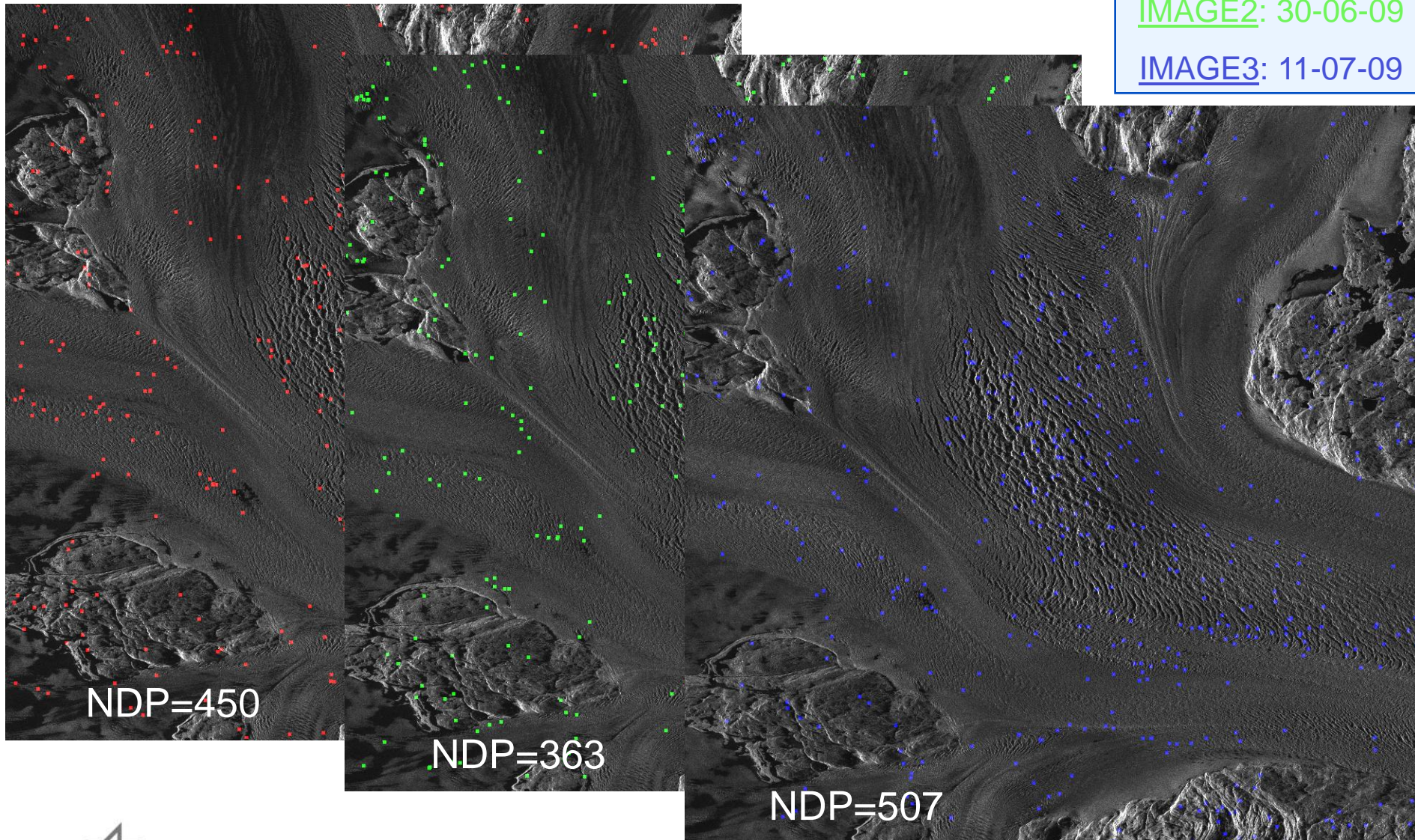


CSs in Time Series

IMAGE1: 19-06-09

IMAGE2: 30-06-09

IMAGE3: 11-07-09





CSs in Time Series (II)

IMAGE 1 - 2

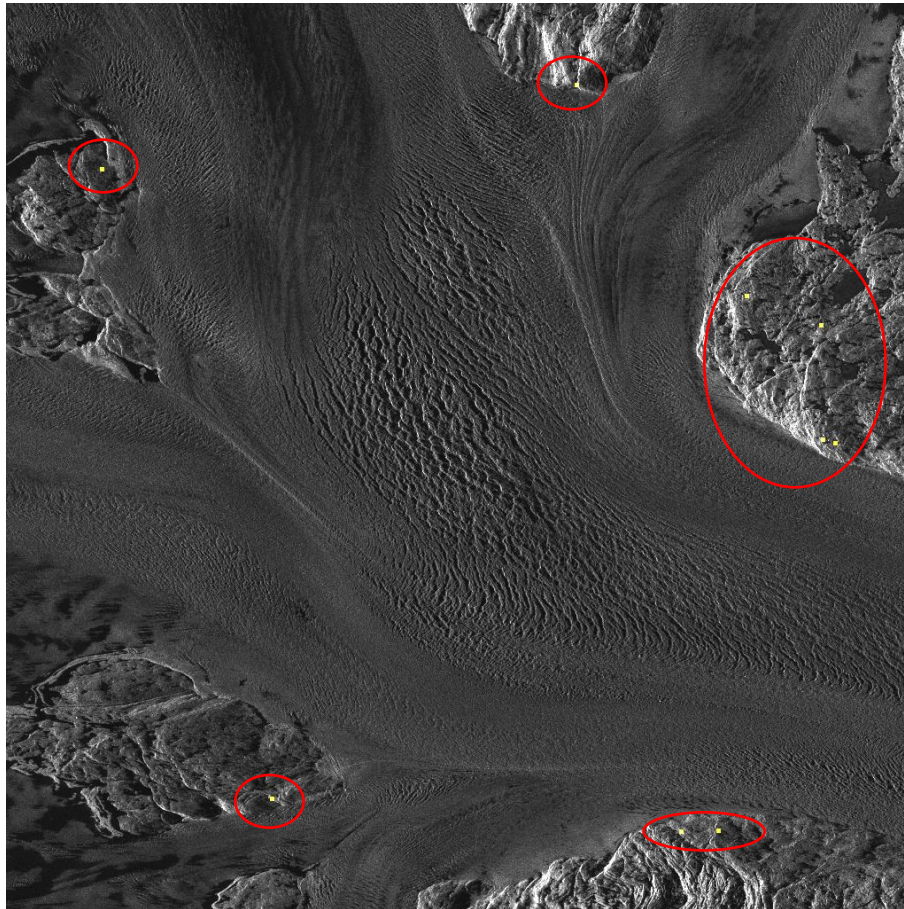
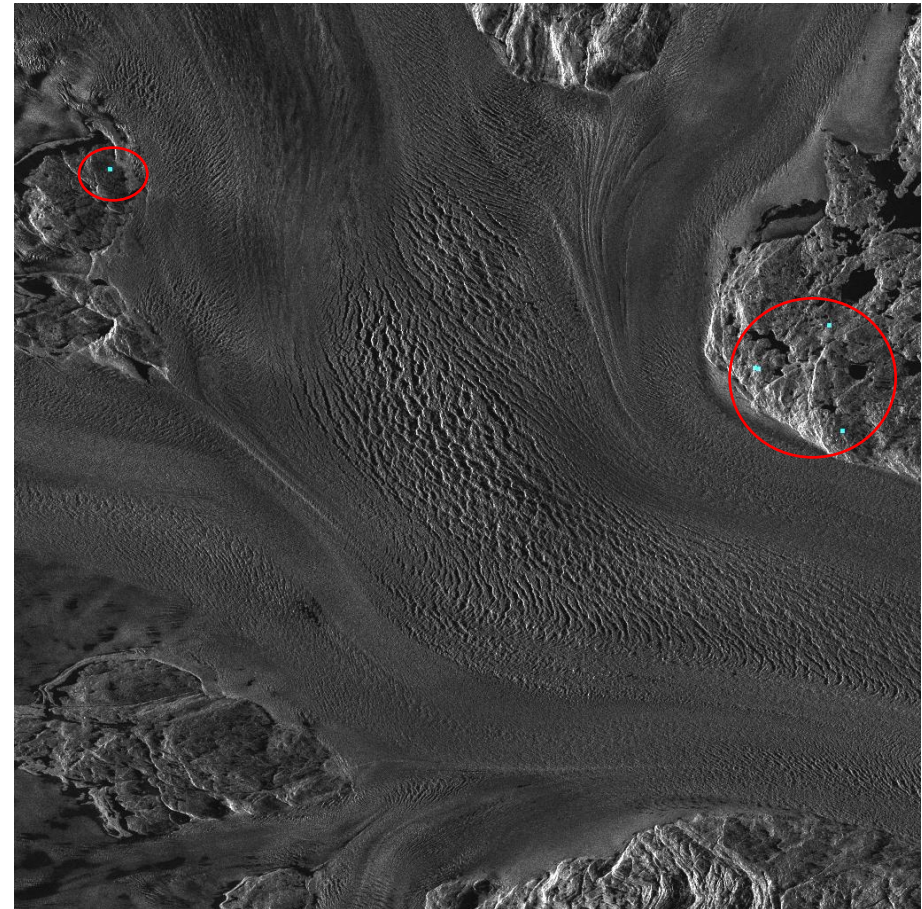
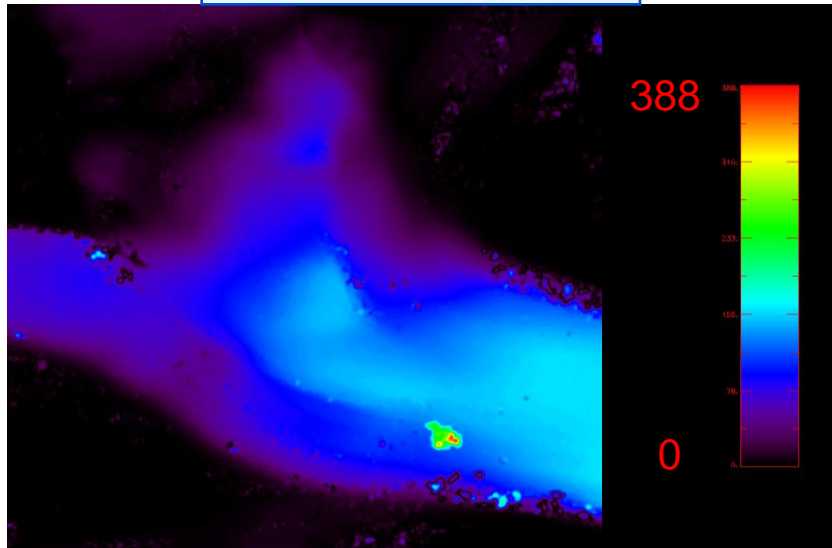


IMAGE 2 - 3

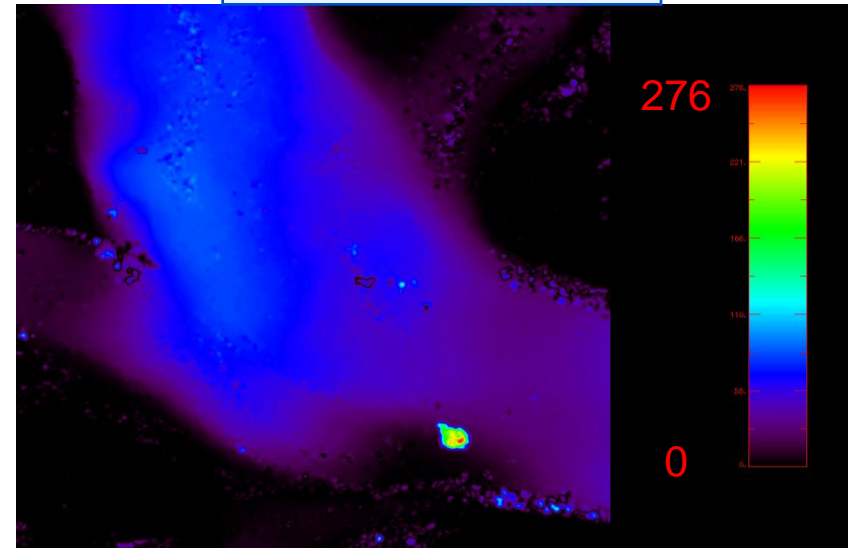


CSs in Time Series(III)

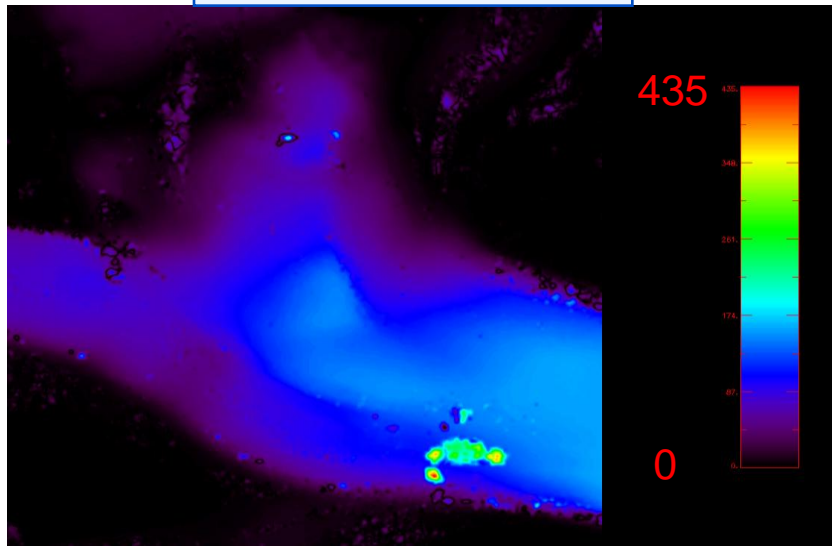
RG SHIFT IMAGE 1-2



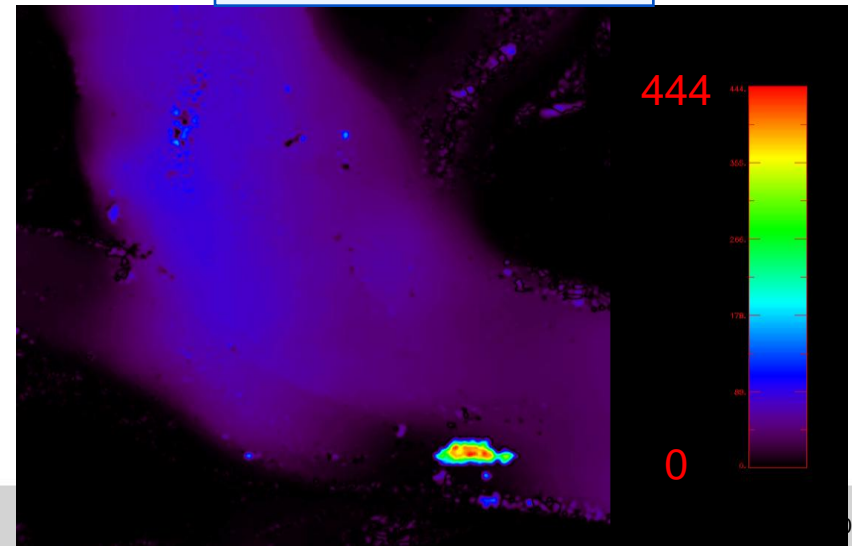
AZ SHIFT IMAGE 1-2



RG SHIFT IMAGE 2-3



AZ SHIFT IMAGE 2-3

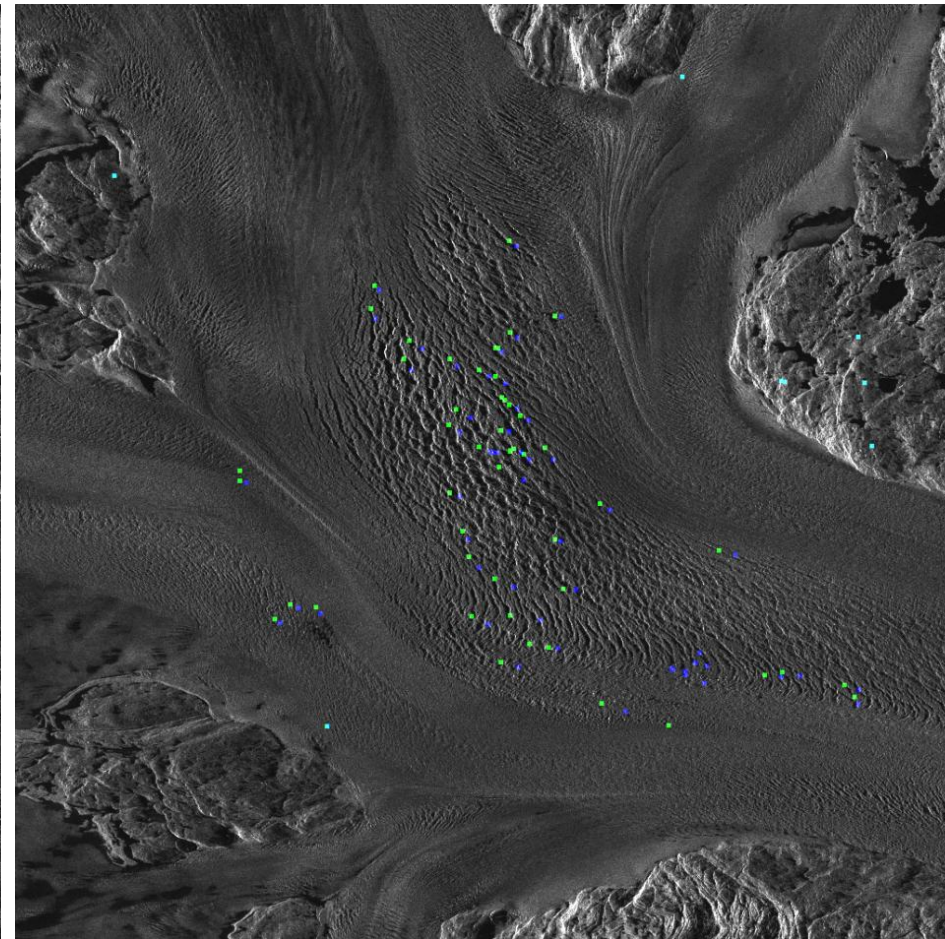
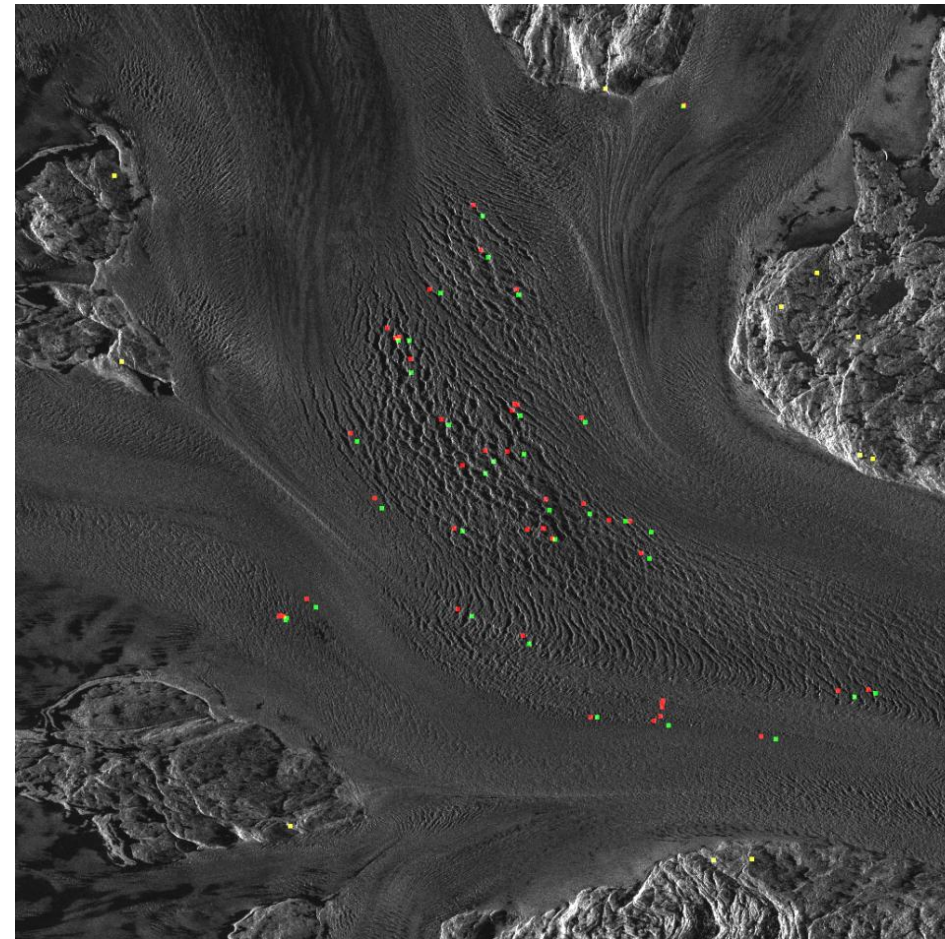




CSs in Time Series (IV)

IMAGE 1 - 2

IMAGE 2 - 3





Conclusions

- ❑ CSs (i.e. quasi deterministic scatterers with partial developed speckle pattern) can be detected in natural (extended) scattering environments by means of (high resolution) space-borne SAR data:
 - Detection on the Helheim glacier using TerraSAR-X time series images.
- ❑ CSs in natural scattering environments can be potentially used for calibration and/or bio-geophysical parameter estimation.
- ❑ Natural CSs are characterised by low(er) SCR levels (i.e they are less deterministic than man-made CSs in urban areas).
 - False Alarms (FA) suppression becomes an issue for their detection.
 - Wide Range/Azimuth bandwidths are an advantage.
 - The combination of Range/Azimuth correlation can be used for FA suppression.
- ❑ Natural CSs have a limited “life time” due to the temporal and/or dynamic environmental effects within the scene:
 - CSs at high(er) frequencies (X-band) live short(er).
 - Detection in multiple images depends on the temporal separation of the images.
- ❑ FA and CSs mortality make the identification (especially within dynamic environments) challenging.